

# **Episodic Memory in Soar**

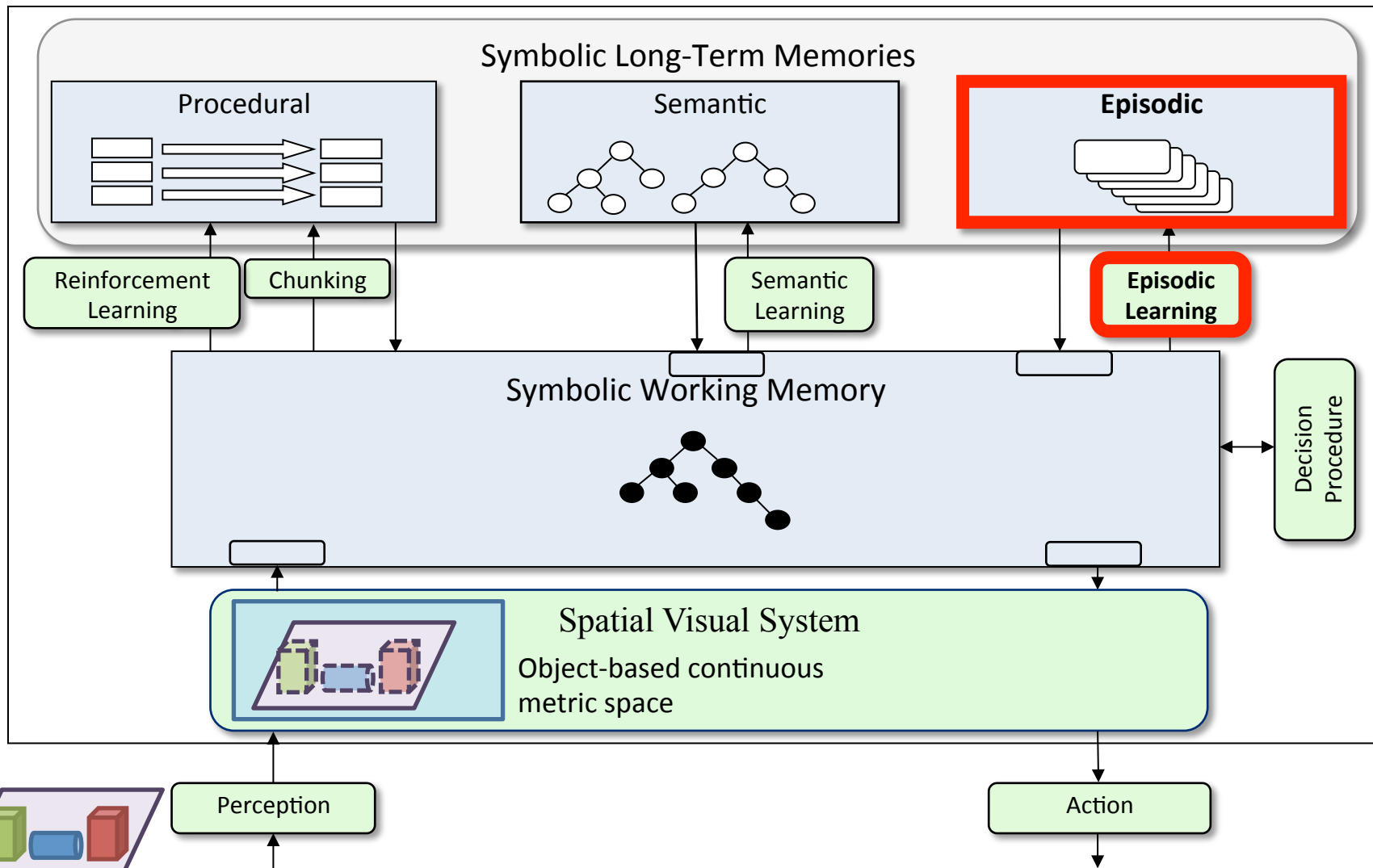
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# Agenda

- Episodic memory as a learning mechanism
- Basic usage
  - Example: TankSoar
- Scaling real-time performance
  - Multi-domain: linguistic, planning, robotics, games

# Soar 9

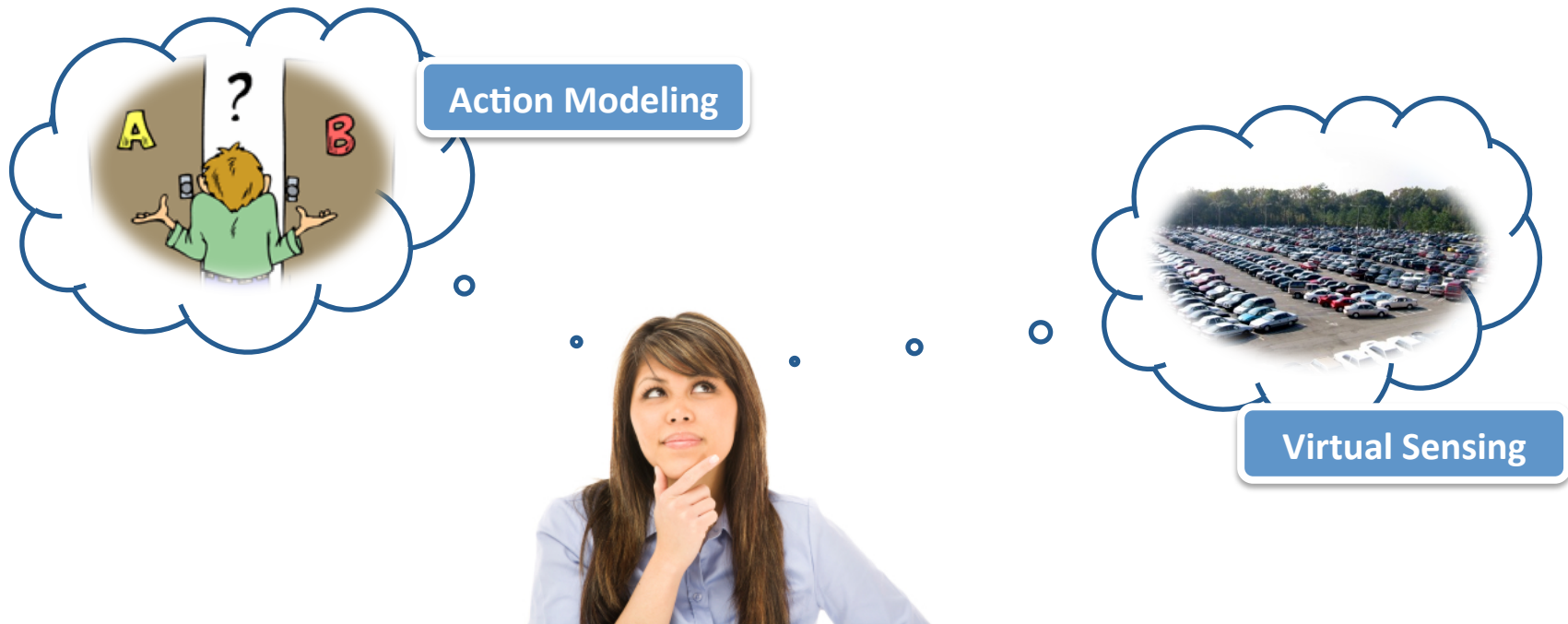


11 July 2013

Soar: Episodic Memory

# Episodic Memory

Long-term, contextualized store of specific events (Tulving, 1983)



# Episodic Memory in Soar

A weak learning mechanism

- Automatically captures, stores, and temporally indexes agent state
- Provides content-addressable agent interface to autobiographical prior experience
- Supports a general set of cognitive capabilities

# Episodic Memory

## *Integration*

### Representation

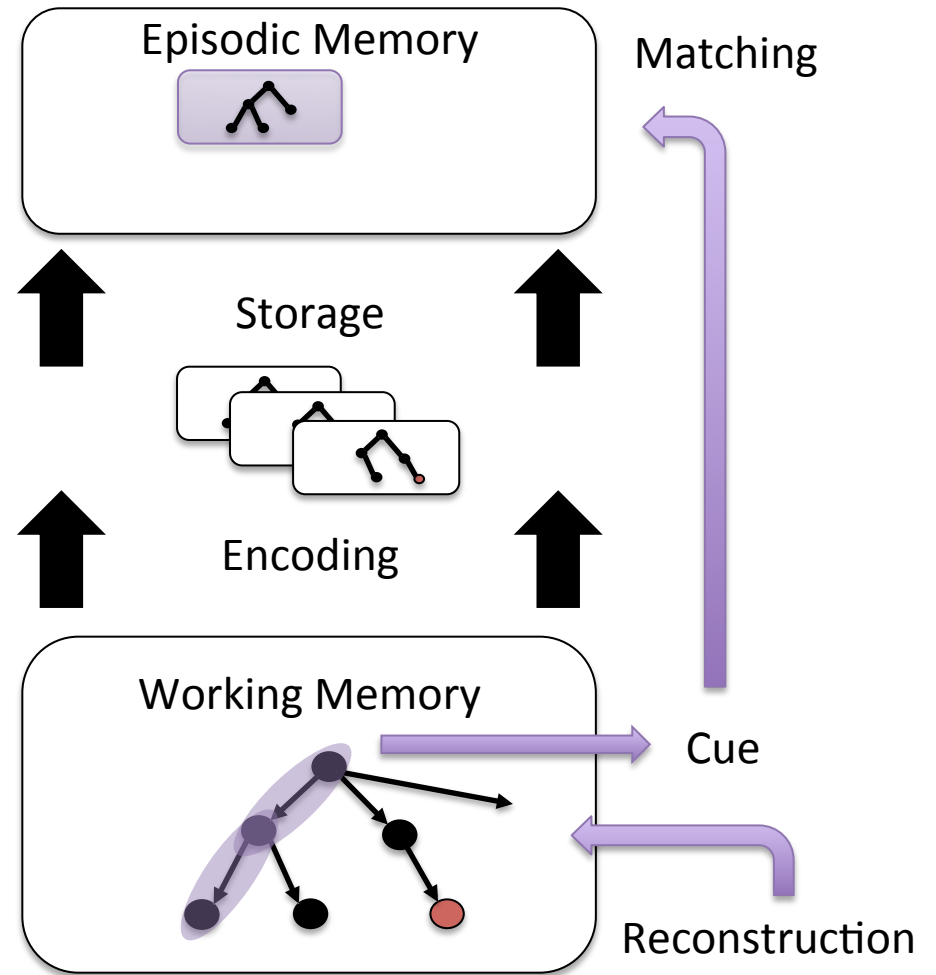
- Episode: connected di-graph
- Store: temporal sequence

### Encoding/Storage

- Automatic
- No dynamics (e.g. forgetting, blending, ...)

### Retrieval

- Cue: acyclic graph
- Semantics: desired features in context
- Find the most recent episode that shares the most leaf nodes in common with the cue



# Basic Usage

- Working-memory structure
- Episodic-memory representation
- Storing knowledge
- Retrieving knowledge

# Working-Memory Structure

Soar creates an `epmem` structure on each state

Each `epmem` structure has specialized substructure

- `command`: agent-initiated actions
- `result`: architectural feedback
- `present-id`: current episode number (more later)



# Episodic-Memory Representation

Similar to working memory: symbolic triples

- Structures within an episode are connected; separate episodes are disconnected

```
(<id0> ^epmem <id4>  
      ^io <id1>  
      ^reward-link <id5>  
      ^smem <id3>  
      ^superstate nil  
      ^svs <id2>  
      ^type state)
```

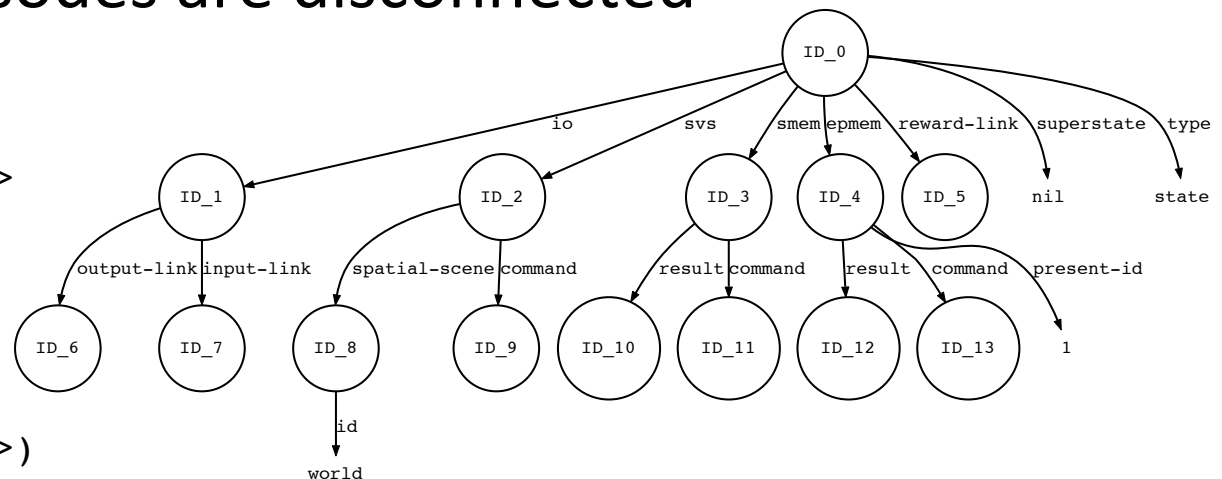
```
(<id1> ^input-link <id7>  
      ^output-link <id6>)
```

```
(<id2> ^command <id9>  
      ^spatial-scene <id8>)
```

```
(<id3> ^command <id11> ^result <id10>)
```

```
(<id4> ^command <id13> ^present-id 1 ^result <id12>)
```

```
(<id8> ^id world)
```



# Storing Knowledge

- **What.** top state of working memory
- **Why.** task-independent trigger
  - `epmem --set trigger << dc output >>`
    - `dc`: decision cycle (default)
    - `output`: new augmentation of output-link
- **When.** at the end of a phase
  - `epmem --set phase << output selection >>`
    - `output` is default
    - `selection` may be useful for in-the-head agents

# Retrieving Knowledge

## Cue-Based

Find the episode that best matches a cue and add it to working memory

## Temporal Progression

Replace the currently retrieved episode with the next/previously encoded episode

## Non-Cue-Based (not covered)

Add an episode to working memory from episode #

Common Constraints (motivated by performance/reactivity):

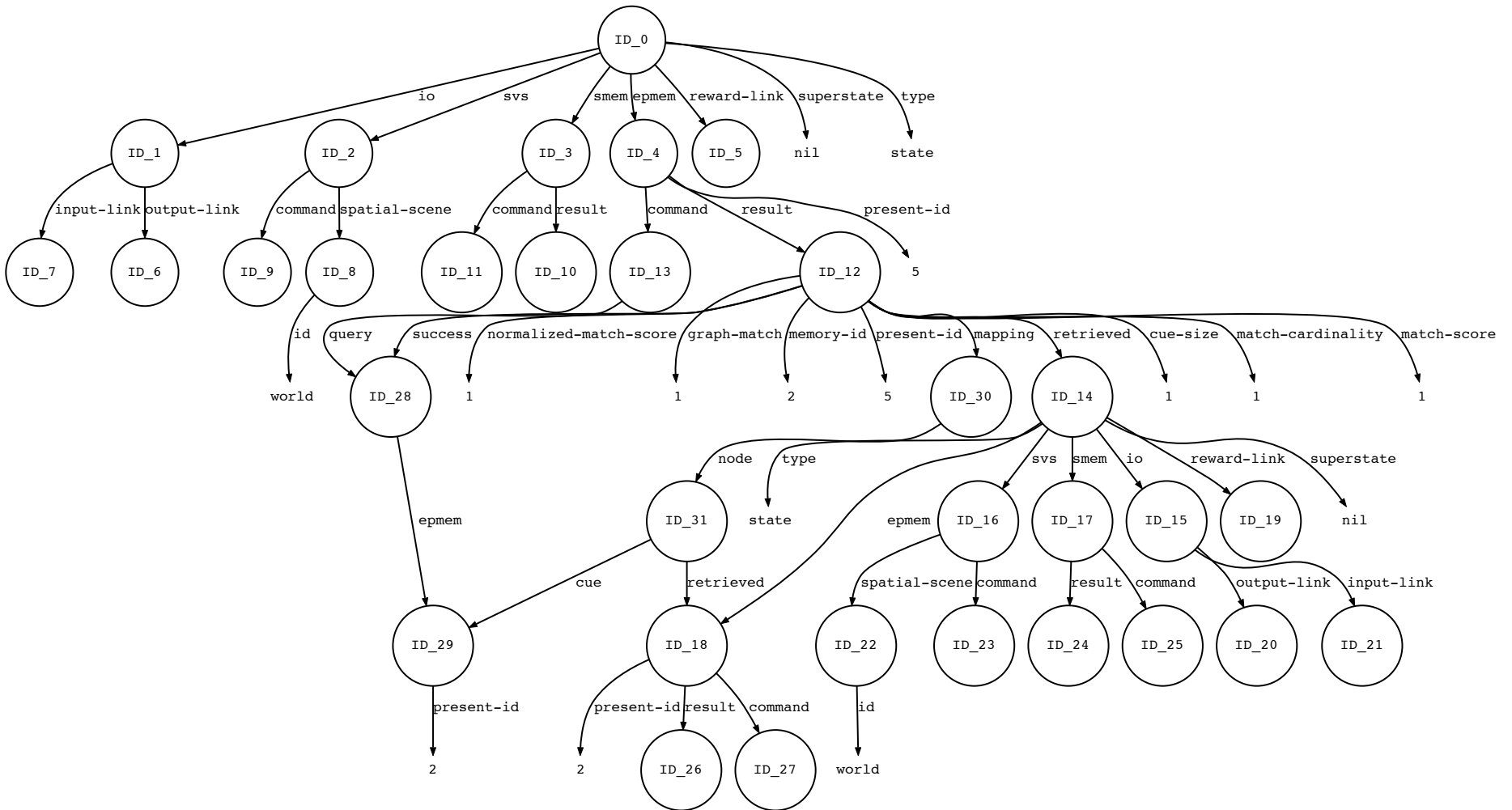
- Only one per state per decision
- Processed during phase (slide 10)
- Only re-processed if WM changes to commands

# Cue-Based Retrieval: Syntax

```
( <epmem> ^command <cmd> )  
( <cmd> ^query <q>  
      ^neg-query <nq> )
```

- The neg-query is optional
- Cues must be acyclic
- The <q> and <nq> identifiers form the roots of episode sub-graph cues
  - query represents desired structures
  - neg-query represents undesired structures

## Example



# Cue-Based Retrieval

## *Optional Modifiers*

(<cmd> ^before time-id)

(<cmd> ^after time-id)

(<cmd> ^prohibit time-id1 time-id2 ...)

Hard constraints on the episodes that can be retrieved.

# Temporal Progression

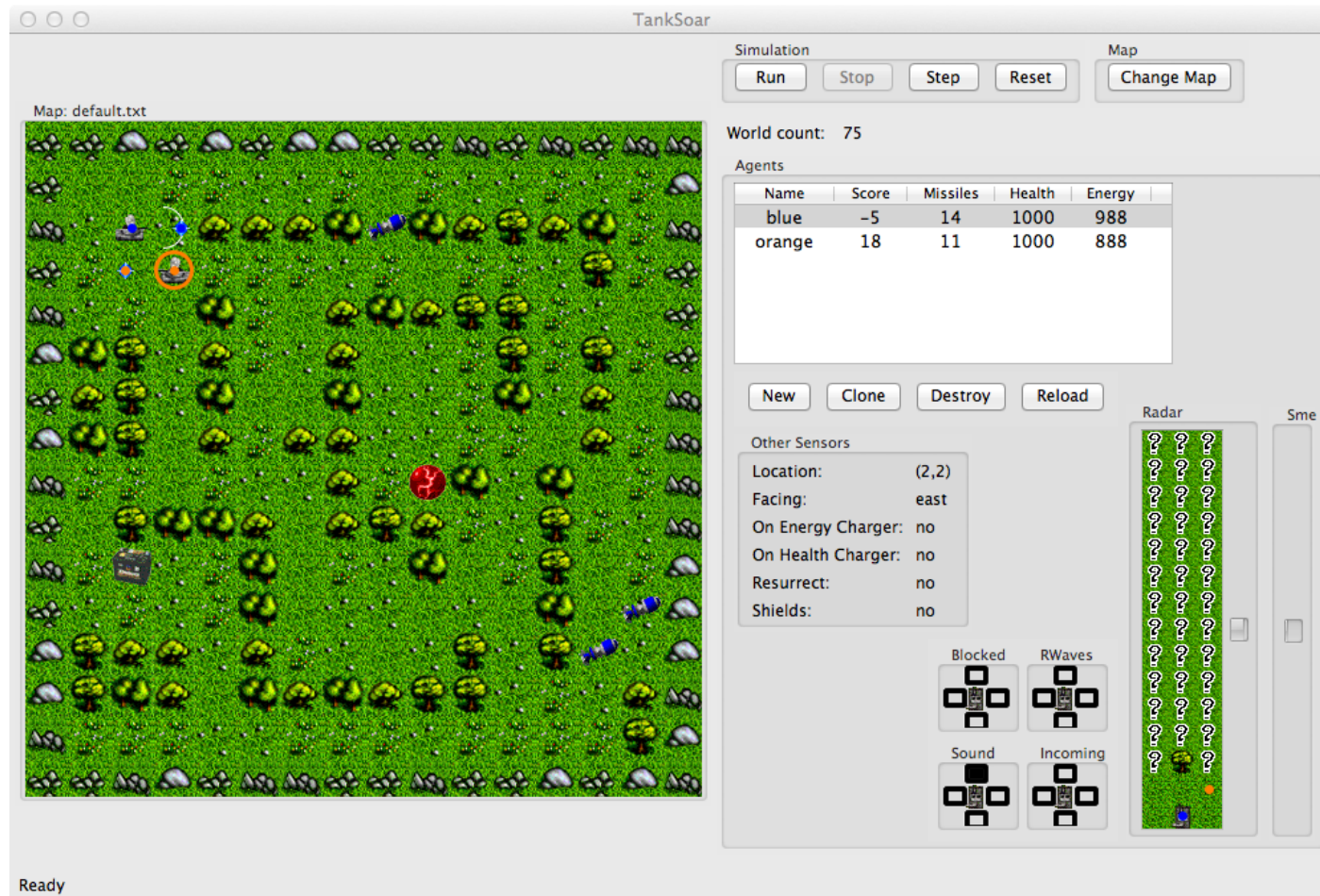
(<cmd> ^next <new-id>)

(<cmd> ^previous <new-id>)

Retrieves the next/previous episode,  
temporally, with respect to the last that was  
retrieved

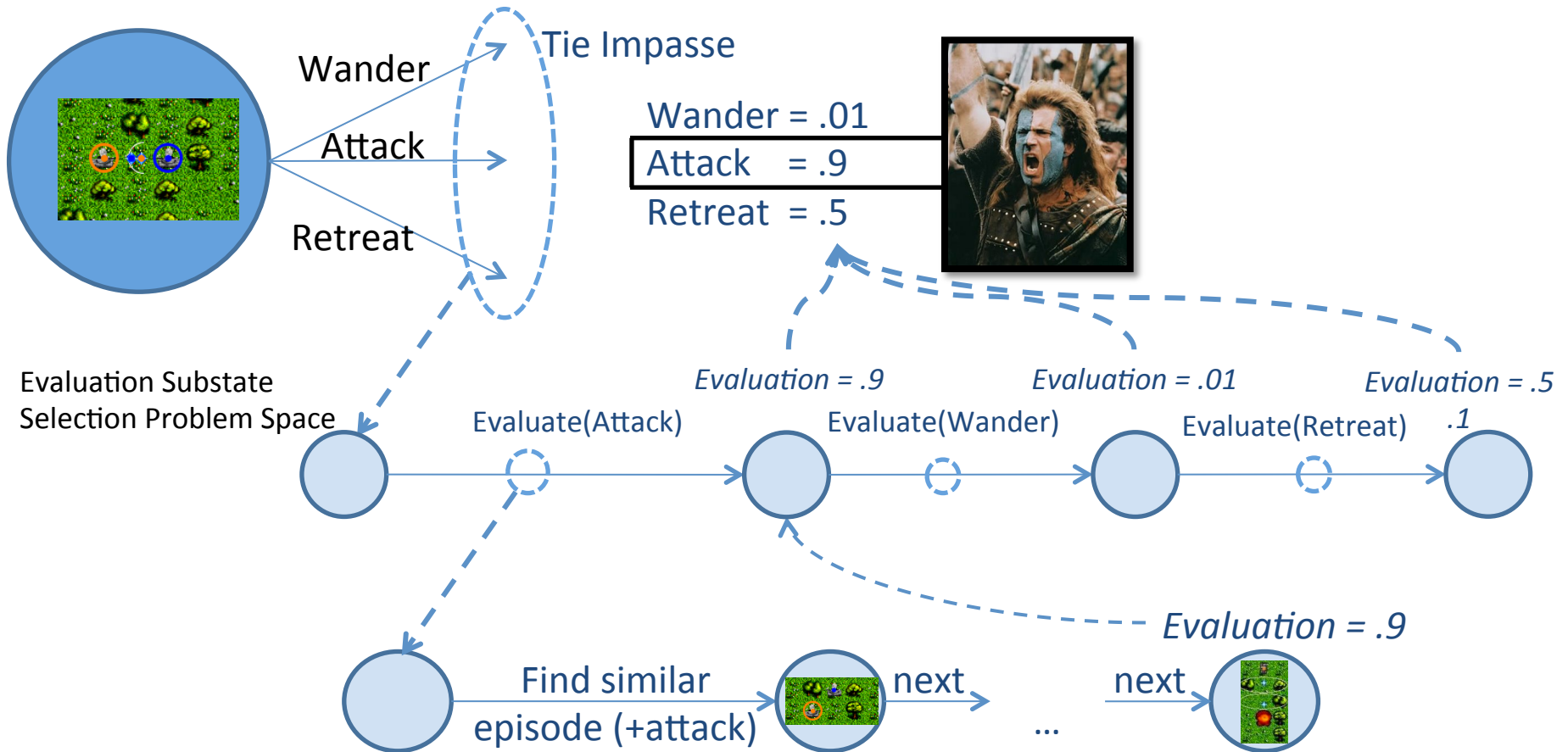
# Example Task

## *TankSoar*



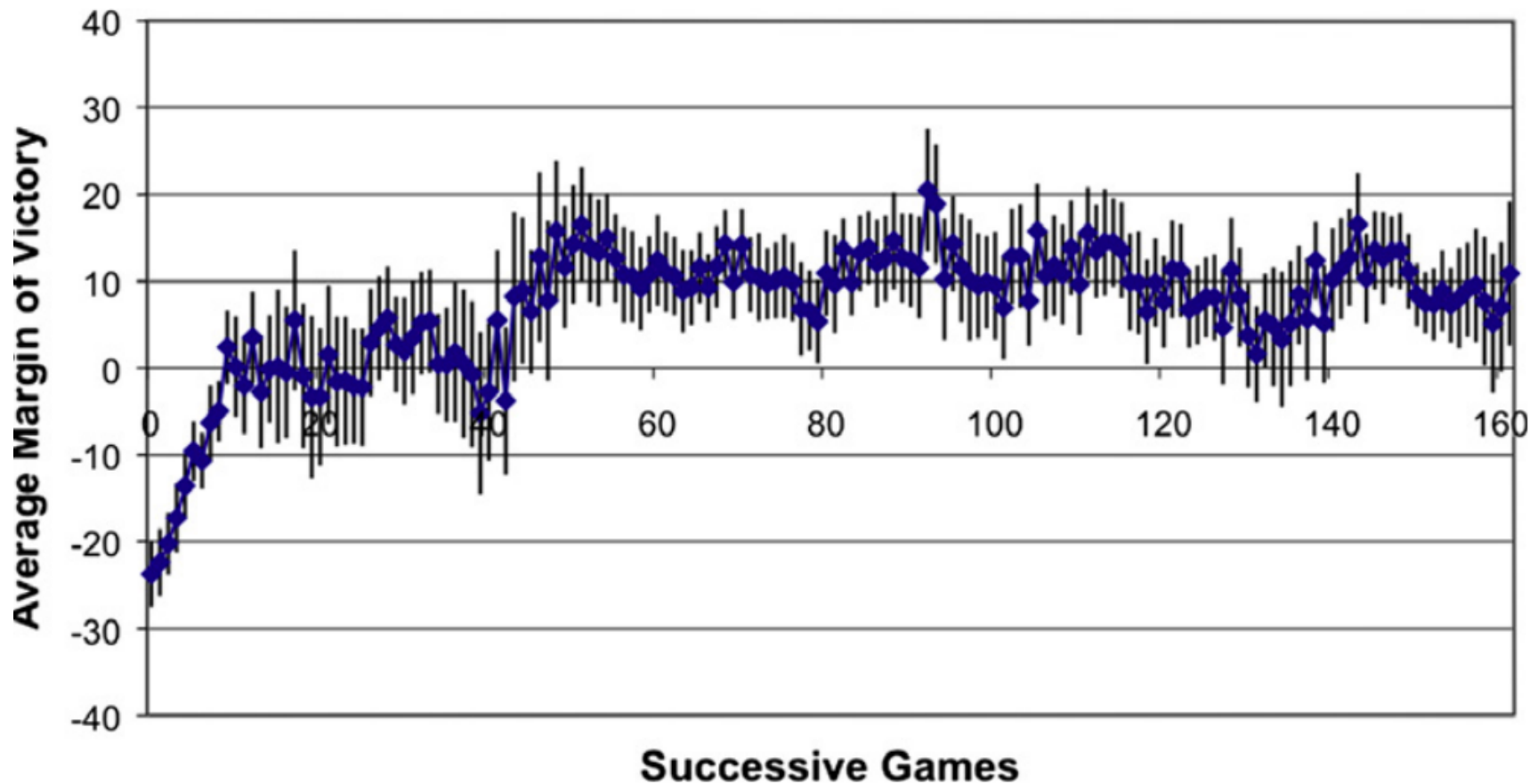


# Using Episodic Knowledge for Subgoal Selection



# Learning from Success & Failure

*A. M. Nuxoll & J. E. Laird, 2012*



# Episodic Memory

## *Computational Challenges for Scaling RT Agents*

Arbitrary, dynamic state

Scaling potential, agent...

- state (1000s nodes/edges)
- life ( $10^6$ - $10^9$  episodes  $\sim$  days)

Cue-matching optimality

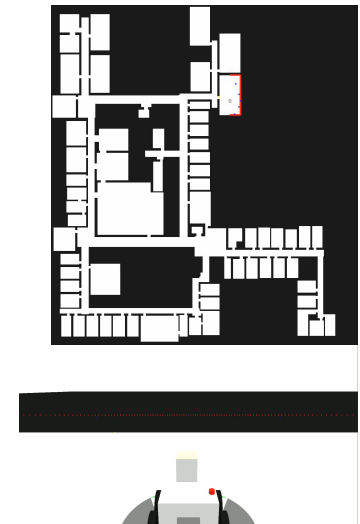
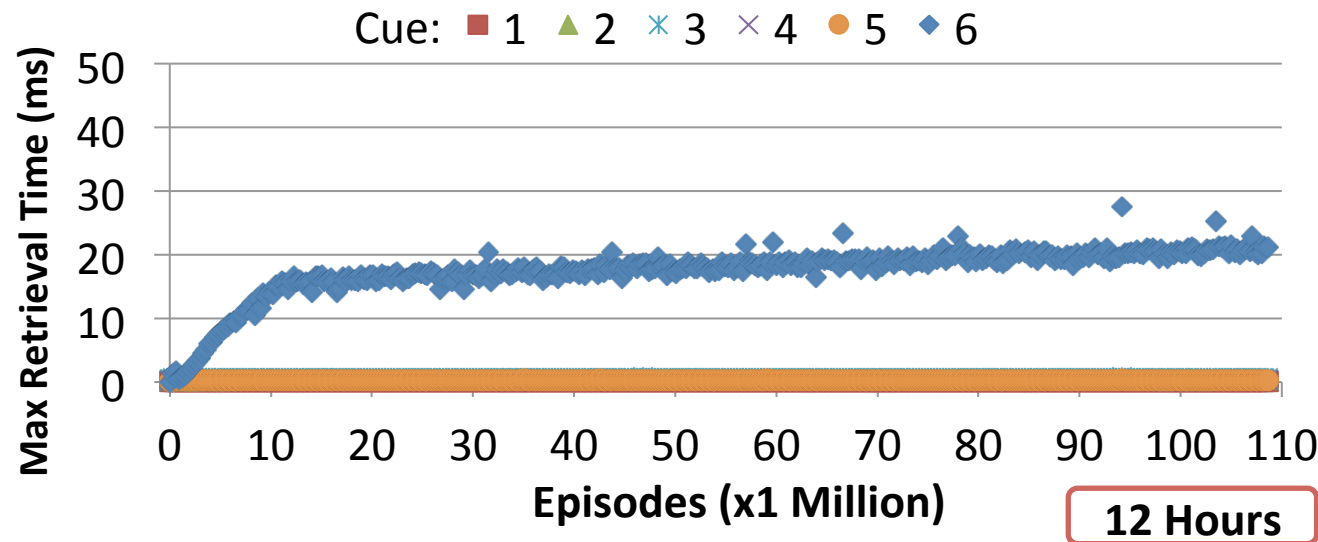
- Constrained subgraph isomorphism (NP-complete)
- Search:  $O(\text{\# episodes})$

# Multi-Domain Scaling Evaluation

## Experimental Setup



- 49 domains: WSD, planning, robotics, games
- $10^5$ - $10^8$  episodes  $\sim$  days of real time, >100 cues



Thank You :)

**Questions?**