# Effective and Efficient Management of Soar's Working Memory via Base-Level Activation

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# Our Focus

#### Human-Level Intelligence

- Long-living, learning, real-time (<50 msec.) agents
- Numerous, complex tasks/environments
- NOT modeling human behavior/processes

### **Cognitive Architecture**

- Computational infrastructure for intelligent agents
- Aspects of cognition that are constant over time and across different application domains

# The Soar Cognitive Architecture



## Soar: LT Memory Access



The reactivity of a Soar agent is the time required to make a decision, which includes accessing and modifying long-term memories

# **Small Working Memory**

### **Necessity**. Bounding Memory Retrievals



#### **Opportunity**. Efficient LT Memory Access



# **Working Memory Maintenance**



### **Maintenance Model**



Evaluating the Efficiency of a Maintenance Mechanism

- Number of elements in working memory (N)
  Large memory: **↑**N
- Number of activations/cycle (E)
  Dynamic, knowledge-rich agent: **↑**E
- Element lifetime (L)
  - Frequently accessed elements: **↑L**
  - − High element turnover: ↓L

# Naïve Approach

### <u>Algorithm</u>

- At each time step
  - For each memory element
    - If (Activation < Threshold)</p>
      - » Forget

#### **Efficiency Evaluation**

- Per Time Step: O(N)
- Per Memory Element: O(L)

# **Our Approach: Decay Prediction**

<u>Algorithm</u> ~ (Nuxoll et al. 2004)

- On new activation event
  - *Predict* time of future decay
  - Add to *time-step-keyed map*
- Each time step
  - Remove keyed decayed elements in map

#### **Efficiency Evaluation**

— Per Time Step: O(# decayed + E\*[Prediction Cost])

# **Decay Prediction**

- 1. Cheaply approximate decay on each access
  - Underestimate time of decay by treating each memory access independently: O(1)
- 2. Exact determination
  - Binary parameter search: O(log<sub>2</sub>L)
  - Not needed if element is removed by #1 estimate
  - Otherwise, <u>reduced</u> by the degree to which #1 is accurate

### Decay Prediction Example



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### Decay Prediction Example



### Novel Base-level Decay Approximation

#### Given

constants

- Decay threshold (θ)
- Decay parameter value (d)

and a set of memory accesses...

- Time since access (s)
- Number of accesses (n)

#### solve for ...

• Time till memory decay (t)

#### Algorithm

For each memory access...

$$\ln(n \cdot [t+s]^{-d}) = \theta$$
$$\ln(n) - d \cdot \ln(t+s) = \theta$$
$$\ln(t+s) = \frac{\theta - \ln(n)}{-d}$$
$$t = e^{\frac{\theta - \ln(n)}{-d} - s}$$



## **Mechanism Evaluation**

### 1. Synthetic

50k random, valid histories

### 2. Mobile Robotics

## Synthetic: Approximation Quality



### Synthetic: Prediction Complexity



# Synthetic: Prediction Computation



### Mobile Robotics Task In Simulation

#### **Exploration**

- 3<sup>rd</sup> floor, CSE Building, UM
  - 110 rooms
  - 100 doorways
- Builds map in memory from experience



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## Agent Map Knowledge



#### **Room Features**

- Position, size
- Walls, doorways
- Objects
- Waypoints

#### Activation

- Initial exploration
- Planning/Navigation

# Mobile Robotics Data (1)



With appropriate decay, base-level activation maintains working memory size comparably with task-specific rules

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# Mobile Robotics Data (2)



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# Automatic WM Maintenance

- Takes advantage of multiple memory systems
- Improves agent reactivity
  - Low computational overhead
  - Sound agent reasoning
  - No task-specific knowledge

# **Related Work**

### Modeling

- ACT-R [Anderson et al. 2004]
- Soar [Chong 2003][Chong 2004]

### **Cognitive Benefits**

- Task Switching [Altmann and Gray 2002]
- Heuristic Inference [Schooler and Hertwig 2005]
- Agent Reactivity [This Work]

# Limitations

- Single decay model
  - Are recency/frequency sufficient to capture memory element importance?
- Single task
  - Regularities of spatial locality map well to recency/frequency
  - LTM elements are never inconsistent with WM

# Thank You :-)

**Questions?**